Climate-Friendly Online Shopping Within the Green eCommerce Project: A Fitting Tool To Determine T-Shirt Sizes Using Active Depth Sensing

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Abstract: Within the context of the Green eCommerce project where we build tailored add-ons for webshops to increase climate-friendly shipping, we analyzed reasons for returns using a modified rule learning algorithm but found no actionable rules. However, since many returns are driven by wrong size information, we have also developed a prototype Fitting Tool app that uses active depth sensing to measure several relevant body measurements and uses these to estimate T-Shirt sizes. Although these body measurements could be shown to be quite precise, T-Shirt sizes could only be predicted at low accuracy. On the other hand, self-reporting by test users showed that the perceived accuracy was considered 1.5-3x higher. Analyzing this issue, it was found that the reason for this is most likely manufacturer bias in reported size, which will be addressed in future work.

1 INTRODUCTION

In recent years, online shopping has increased rapidly. This trend was also being fuelled by the Covid 19 pandemic and, according to many experts, will continue unabated in the future. As a result, e-commerce in the Business-to-Consumer (B2C) sector recorded record figures in 2021 in terms of turnover (9.6 billion euros in Austria according to Knabl et al. (2021)) and in terms of postal parcels delivered (Sievering, 2020). However, this flood of parcels goes hand in hand with the many negative consequences of a rapidly growing volume of goods transport on the last mile, which manifest themselves in traffic jams, noise pollution, air pollution and a decreasing quality of stay in public spaces.

Many study authors (BMVIT, 2015; DCTI, 2015; BMK, 2020; Kolf, 2021) come to the conclusion that online shopping only has a better ecological balance than shopping in stationary retail stores under optimal framework conditions (e.g. promotion of collective orders, climate-friendly means of transport and avoidance of return shipments and same-day deliveries). However, the package delivery situation is currently characterized by frequent multiple deliveries, climate-damaging and underutilised means of transport and, above all, high return rates, which amount to up to 47% in the Austrian clothing sector (Knabl et al., 2021). On the demand side, the situation is aggravated by the fact that end consumers in online shops are often offered no or only very limited climate-friendly delivery options, which contradicts the increasing sustainability awareness (Holtmann and Klitzsch, 2021) of many end customers.

This is where the preventive and customeroriented approach of the *Green eCommerce* research project (Wernbacher et al., 2023) comes in. Within a continuation of the previous project *Think!First* (Wernbacher et al., 2019), contextually tailored addons based on behavioural, technology-based and logistical interventions for the existing online shops of the participating partners are designed, developed and tested in practice. With the help of an unique combination of a gamified loyalty system that rewards users for high compliance, persuasive design principles that are characterized by visually highlighting regional products with short delivery routes or collective orders, as well as AI-supported fitting tools and chat bots that automatically measure clothing sizes and point out environmentally friendly delivery options, customers are encouraged to shop more consciously – in the sense of a traffic shift, traffic avoidance and traffic optimisation.

Through the active participation of the practical partners *Julius Meinl am Graben, kauftregional* and *ZERUM*, the innovative add-ons can be tested comprehensively and practically for different objectives, target groups and different product groups in real operations over several months. In addition, the integration of the innovative logistics service *Green to Home* from logistics partner *ERIVE* makes it possible to analyze the entire process between online shop operators, online end consumers, and package delivery service providers. Thus, this holistic approach generates new and in-depth insights into the acceptance, suitability and impact of innovative interventions in online shops.

Non-fitting garments are also a known factor to strongly drive returns (Kristensen et al., 2013; Singh, 2015). To obtain precise body measurements, we developed a Fitting Tool in cooperation with partner *ZERUM*. The Fitting Tool is an Android app that runs on a small subset of mobile phones with active depth sensing cameras. Due to the ability of such cameras to exactly measure distances it was possible to rapidly develop a prototype app to obtain body measurements directly from depth images, using a pretrained body pose keypoint detector.

In this paper we focus on reducing returns, both by characterizing rules and by obtaining precise body measurements using the Fitting Tool. We initially describe our results on using understandable machine learning to analyze reasons for returns. In this project, only *ZERUM* tracked and expressed concerns with high returns, so we focus on its returns data. The analysis follows (Seewald et al., 2019) and also uses the modified rule learning algorithm presented there.

Concerning the Fitting Tool, we first present an algorithm to exactly measure body sizes from depth camera images and body pose estimates and evaluate its accuracy on a small set of persons. We then use a subset of these measurements to determine T-shirt sizes using a standard size table as well as machine learning algorithms.

2 RELATED RESEARCH

Zalando Corporate (2023) introduced a new feature in their app that measures body shape by one front and one side photo of a person in tight-fitting clothes. It is based on technology by company Fision which was acquired by Zalando in 2020. Processing is locally on the smartphone and photos are deleted afterwards. The exact measurements are then used to search for fitting clothes. Currently, only women's tops - including dresses - can be searched for. Contrary to our approach, their approachs works on any smartphone and does not require special sensors. However, no quantative data on the precision of the obtained measurements were reported and the integrated search is likely optimized to deal with the expected inaccurate measurements. The requirement for tight-fitting clothes is something that our system also needs as depth cameras cannot see through clothes.

Singh (2015) analyzed reasons for returns within Indian online market Flipkart, where mainly womens' garments are sold directly by the manufacturers. Apart from a detailed analysis of returns reasons they also provided a minimal set of measurements for size tables to reduce returns.¹ Simply changing the shown size tables for nine manufacturers according to his recommendations reduced returns dramatically: An average reduction of absolute returns rate of 9% was reported with a maximum of 46% – so manufacturers saw their returns rate at best almost halved. They also provided an analysis of returns reasons due to product quality issues which were also a major cause for returns within this online market, albeit less relevant for our project.

Kristensen et al. (2013) present TrueFit, a system to determine precise body measurements which can reduce returns by up to 30%. However it requires much effort by potential customers. TrueFit works by combining extensive information provided by customers on their height, age, weight as well as a set of previously bought fitting clothes with manufacturer, model type and given size to determine best fit. While it therefore tries to compensate both customer and manufacturer bias, in its present form it ignores body size temporal drift (i.e. changes in body size over time).

¹Minimal set of measurements: breast width, waist circumference, shoulder circumference, sleeve diameter at $\frac{3}{4}$ height; provide at least UK, US and EU-Sizes and at least S,M,L,XLL for simple sizes.

Toktay (2003) analyzed different models to predict returns via synthetic data. They differentiated between modelling via periodical data where only the number of sold and returned products is known (i.e. where it is not possible to identify products and determine exactly which products were returned), and modelling via individual data on product level (i.e. where such a identification is feasible). For the second case – which corresponds to our data – they proposed an Expectation Maximization model. No explicit modelling of the reasons for returns took place.

3 CHARACTERIZATION OF RETURNS

ZERUM provided a list of 2,543 articles ordered of which 325 had been returned. We combined the following data on products into one dataset:

- Order information: Data and time of order and payment, total amount paid, taxes by category, customer, shipping and billing address.
- **Product information**: Label, size, material, price per item, description, manufacturer name.

Due to the small amount of data we used a random sample of one third of the data (678 samples) biased towards a higher proportion of returns (203 of the 325 returns) for training and two thirds (1,865 samples with 122 returns) for testing. Initial experiments led us to remove features that are redundant, those with unique and almost unique id values, and the field payment state which partially leaks the returns status and thus yields unrealistically high predictive performance.

The fields material, size, description, label, billing address, shipping address and customer were free text fields containing multiple words. We initially considered creating combined or separate word vectors for them, however performance as measured by balanced F_1 was always worse.

We characterized returns by the modified version (described by Seewald et al. (2019)) of the wellknown rule learning algorithm, JRip, which is an Open Source implementation of RIPPER (Cohen, 1995) within the data mining suite WEKA (Frank et al., 2005). We chose JRip for its ability to produce small concise rule sets that are easy to interpret.

We obtained a rule set with only three rules that gives a precision of 0.247, recall of 0.385 and a balanced F_1 measure of 0.301 on the test set – unfortunately not much better than random guessing. Furthermore, the obtained rules did not make empiricial

sense so we do not describe them in detail. We also tested three other algorithms from the WEKA suite: SMO, a support vector machine classifier with linear kernel; Logistic Regression; and J48 which is a reimplementation of C4.5; but obtained comparable F_1 measures of 0.270, 0.263 and 0.307 respectively. Deep learning algorithms were not considered due to the smallness of the data set, and also because understandability of the models was a primary requirement.

We therefore proposed to ZERUM to provide better size information in the webshop as it is well known this leads to smaller returns rates (Kristensen et al., 2013; Singh, 2015), and since we also found in earlier work (Wernbacher et al., 2019) that a combination of detailed size tables with persuasive design to emphasize size tables by color and layout (phase II) reduced the returns rate by 10.4%.

4 FITTING TOOL

As it is well known that incorrect size information can lead to returns, and that adding manufacturer size tables to a website can reduce returns significantly (Kristensen et al., 2013; Singh, 2015) by allowing customers to more easily determine whether a clothes item will fit them, we developed a Fitting Tool app to measure body size automatically and thus apply both insights at once.

4.1 HARDWARE

Active depth cameras (Seewald and Pfeiffer, 2022) were an obvious choice for this task, since they allow precise measurements without requiring large amounts of training data that we would not have been able to produce within the scope of this project.

First, to prevent having to use manufacturerspecific interfaces to access integrated depth cameras – which normally need a rooted device and would thus never to able to run on the vast majority of mobile phones – we chose Google ARcore as framework and selected several phones from its compatibility list² which supported Time-of-Flight (ToF) hardware depth sensors. We focussed on ToF as it is the state-of-the-art for active depth sensing and in fact almost all currently available depth cameras use ToF as sensing technology.

Due to view angle and since depth data was only available from a certain minimum distance, the Fitting Tool app needed two persons to operate it: one

²See https://developers.google.com/ar/devices?hl=en



Figure 1: Left: Color image with overlaid OpenPoseestimated body keypoints. Right: Depth image with overlaid estimated body shape due to tracking. Both images were manually cropped to improve visual alignment.

person – the one to be measured – in front of the mobile phone and one person behind it.

4.2 BODY POSE KEYPOINT DETECTION

For detection of human pose keypoints, we chose the Tensorflow Lite model of OpenPose (Cao et al., 2019) since it was easy to integrate into an Android app that uses Google ARcore and also relatively fast (about 0.6s to analyze one 640x480 image). For its body pose detection, OpenPose only analyzed the color image, so it was also necessary to create a spatial mapping from color to depth image. Google ARcore provides such a mapping, however it was insufficiently accurate³, so it was necessary to extend it with a general planar homography correction (Chum et al., 2005). This correction reduced the residual error to 2.41 \pm 1.15 pixels on a 640x360 depth image (i.e. 0.32% when compared with the diagonal) which was deemed acceptable.

4.3 MEASUREMENT MODULE

The distance between body keypoints cannot be directly used to estimate body size measurements, since the position of body keypoints always has some jitter so their relative position versus the body border is by no means fixed, and human bodies are never perfectly flat.

We therefore implemented a 2D tracking/measurement algorithm, *MarkPose* – shown in Alg. 1 – that starts at various body keypoints estimated by OpenPose (already translated to depth image coordinates) and tracks along lines derived from relative keypoint positions until the depth increases sufficiently to ascertain the tracked point is outside the body. Each 2D point in the depth image can be easily converted to 3D by utilizing the ARcoreprovided f_x, f_y, c_x, c_y parameters⁴, which was used to measure the length of corresponding tracked lines based on 3D points, and doubling this value to obtain circumference. The tracking algorithm main function computeMeasurement is shown in Alg. 1 and needs the parameters sP (starting point from body 2D keypoints already converted to depth image coordinates), min/max/stepAlpha (range and steps for local search), *depthDiff* (for body border recognition), and *depthImage* (the depth image to be processed, represented as two-dimensional image with millimeter distance values for each pixel). For computing **SHOULDER**, use sP = Neck, minAlpha = 0.0, maxAlpha = 0.1, stepAlpha = 0.1 and depthDiff =75. For computing WAIST, use $sP = \frac{LHip + RHip}{2}$, minAlpha = -0.25, maxAlpha = 0.25, stepAlpha =0.025 and *depthDiff* = 125.

We also tracked neck, left and right wrist, and left and right elbow in a similar manner but did not use it later for T-Shirt size estimation, so they are not shown here. Fig. 1 shows a sample color and depth image with all tracked keypoints and distances, including the ones not used for T-Shirt size estimation.

This algorithm yielded measurements for a single depth frame in around 2s, already including OpenPose processing. To improve data quality, we recorded 15 frames in sequence (taking about 0.5s) and then analyzed all frames, reporting the arithmetic mean over all measured values, resulting in a total processing time of about 30s. We also tested reporting the median value which performed slightly better. These values were later used for T-Shirt size estimation.

To estimate the proposed system's error, we manually determined **SHOULDER** and **WAIST** measures from five people (three men, two women) using a band measure (unit: centimeters), and compared them with the median values averaged over 15 frames from each person analyzed by our system. **SHOULDER** had an error of $4.1\% \pm 2.34$ versus the true value, and **WAIST** had an error of $4.7\% \pm 4.38$ versus the true value.

 $^{{}^{3}86.65 \}pm 5.61$ pixels difference for eight manually tagged points, however most of the difference seems to have been a scale factor and a translation due to different aspect ratios and sizes between depth and camera image.

⁴See function *get3D()* in Alg. 1

Algorithm 1: Tracking algorithm *MarkPose* with associated helper functions. The main function is *computeMeasurement*.

Function *getDepth(p,depthImage)*

/* Returns depth in millimeters at 2D position $p=(p_x,p_y)$ from depth image. */ return $depthImage_{p_x,p_y}$

end

Function *get3D*(*p*,*depthImage*)

/* c_x, c_y, f_x, f_y are provided by the Google ARcore API. All units are converted from millimeters to meters here. */

 $\begin{aligned} z' \leftarrow & \frac{getDepth(p,depthImage)}{1,000};\\ x' \leftarrow & z'\frac{p_x - c_x}{f_x};\\ y' \leftarrow & z'\frac{p_y - c_y}{f_y};\\ & \begin{pmatrix} x' \end{pmatrix} \end{aligned}$

 $p3D \leftarrow$

return p3D;

end

Function *getDist(s3D,e3D)*

/* Standard vector distance between two 3D points return |s3D - e3D|;

end

end

Function *computeMeasurement(sP,minAlpha,maxAlpha,stepAlpha,depthDiff,depthImage)*

```
l \leftarrow Neck - \frac{LHip + RHip}{2};
l' \leftarrow l \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \frac{1}{|l|};
maxDist \leftarrow 0;
for \alpha \leftarrow minAlpha; \alpha \leq maxAlpha; \alpha \leftarrow \alpha + stepAlpha do
     sP' \leftarrow sP + \alpha * l;
     initialDepth \leftarrow getDepth(sP, depthImage);
     sLeft \leftarrow sP'; stepLeft \leftarrow 0;
     while getDepth(sLeft,depthImage) < initialDepth+depthDiff do
          sLeft \leftarrow sLeft + l'; stepLeft \leftarrow stepLeft + 1;
     end
     sRight \leftarrow sP'; stepRight \leftarrow 0;
     while getDepth(sRight, depthImage) < initialDepth+depthDiff do
          sRight \leftarrow sRight - l'; stepRight \leftarrow stepRight + 1;
     end
     if stepLeft > 0 and stepRight > 0 and \frac{min(stepLeft, stepRight)}{max(stepLeft, stepRight)} \ge 0.5 then
          s \leftarrow sRight; dist \leftarrow 0; s3D \leftarrow get3D(s, depthImage);
          while s \neq sLeft do
               s \leftarrow s + l'; e3D \leftarrow get3D(s, depthImage);
               localDist \leftarrow getDist(s3D,e3D);
               dist \leftarrow dist + localDist; s3D \leftarrow e3D;
          end
          if dist > maxDist then maxDist \leftarrow dist;
     end
end
return maxDist * 2;
```

*/

Table 1: Fixed size table that was initially used for T-shirt size estimation. All units in cm.

Size	SHOULDER	WAIST
XS	45.0	65.0
S	48.0	67.0
Μ	51.0	69.0
L	54.0	71.0
XL	57.0	73.0
XXL	60.0	75.0

4.4 T-SHIRT SIZE ESTIMATION

Initially we used a fixed size table for **SHOULDER** and **WAIST**, see Table 1. For T-Shirt size estimation we chose the smallest size where both measured values – **SHOULDER** and **WAIST** – were below the corresponding values according to the size table.

At the time of writing this paper, we had obtained data set with 73 different persons with known (self-reported) T-Shirt sizes. On this dataset, using the fixed size table from Table 1, an accuracy of only 21.91% was obtained.

To improve on this, we reformulated this task as a machine learning problem, mapping the measured body sizes **SHOULDER** and **WAIST** (as arithmetic mean over the measured 15 frames) to the known Tshirt size. To enhance the data set, we added additional features, namely the median of each measurement (computed over the 15 analyzed frames) and also included standard deviation for each mean, plus the number of samples that could be processed (i.e. which were not excluded by tracking errors). In this way we obtained a model with three rules and an leave-one-out cross-validation accuracy of 43.66% which is much better but still not satisfactory.

```
(shoulderMedian <= 0.94) => class=XS
        (20.0/9.0)
(waistMedian <= 0.76) => class=S (6.0/2.0)
        => class=XL (45.0/41.0)
```

Currently, we are awaiting new data to test this model. However it should be noted that the new model only predicts XS, S and XL – three of six classes – and no other sizes, contrary to the size table-derived mapping.

Undetected tracking errors may explain the unsatisfactory performance observed above. However a manual analysis of 50 randomly chosen depth images indicated that for 80% both measurements **SHOUL-DER** and **WAIST** were correct; 14% had a tracking error for **SHOULDER** (it was too short) and 6% had a tracking error for **WAIST** (it was too long, in most cases because hands were too near to the waist and were measured together with it). Assuming these er-



Figure 2: T-Shirt sizes reported by users versus **SHOUL-DER** and **WAIST** measured sizes. Both **SHOULDER** and **WAIST** measures are the arithmetic mean of at most 15 local measurements from the same person, each computed from one of the 15 consecutively recorded depth images. More details see text.

rors are randomly distributed, the expected error after averaging 15 frames is negligible.

Surprisingly, the qualitative evaluation reported by the measured people themselves via questionnaire directly after the measurement was much better. 33.33% of people reported the measurement as *ok*, 27.78% as *partially ok* and 38.89% as *incorrect*. So about 61.11% of the people considered the reported Tshirt size to be *ok* or *partially ok* which is three times better than would be expected from above quantitative estimate when using the standard size table and still about 50% better than the machine learning model from above.

Manufacturer bias may explain this discrepancy as people may consider more than one size to fit, depending on manufacturer and model. To test this hypothesis, a visualization of actual measurements versus user-reported T-shirt sizes was created. Fig. 2 shows a plot of SHOULDER versus WAIST with the reported sizes as differently shaped points, using arithmetic mean to average measurements of the 15 recorded depth images from each person. Fig. 3 shows the same data but uses median instead of mean for averaging. It can be seen at first glance that no clear definition of sizes depending on either **SHOULDER** or **WAIST** – or both – can be obtained. The most likely explanation is therefore that different manufacturers define T-Shirt sizes differently (perhaps even for different models), so these are not universally comparable. In fact one tester mentioned that he often buys T-shirts in two different sizes from different manufacturers but all of them fit.



Figure 3: T-Shirt sizes reported by users versus **SHOUL-DER** and **WAIST** measured sizes. Both **SHOULDER** and **WAIST** measures are median values of at most 15 local measurements from the same person, each computed from one of the 15 consecutively recorded depth images. More details see text.

5 CONCLUSION

We have introduced the Green eCommerce project, which is concerned with reducing returns and encouraging customers to shop more environmentalconsciously.

In the preliminary part of this paper, we have characterized reasons for returns using compact rule lists as in earlier work. However, the obtained rules were not suitably precise which is most likely due to the much smaller dataset available here, and could not be translated into actionable items. We therefore suggested actions known to reduce returns from earlier work.

In the main part of this paper we have described the Fitting Tool app, to exactly measure body parameters using an active depth camera. We found that direct body measurements (in cm) were quite precise, however T-Shirt sizes could only be predicted at a much lower accuracy from this data either by a fixed size table or a machine learning model. However, feedback by users indicated that the perceived performance of the system is about 1.5-3 times higher. This may be explained by manufacturer and/or model bias, leading to non-comparable T-Shirt sizes between manufacturers or models and also making people more likely to consider more than one predicted size as fitting. Manufacturer bias of this kind was also found in earlier work by Seewald et al. (2019).

5.1 FUTURE WORK

The main issue with the proposed Fitting app is that T-shirt sizes can only be predicted at low accuracy due to manufacturer bias. We aim to resolve this by using manufacturer-dependent size tables – either embedded into the app itself and additionally chosen by the user, or embedded into the webshop while restricting the app to search for fitting garments by using the more precise body measurements instead of the estimated T-shirt size. The latter would have the additional advantage to allow normal webshop users to also search by exact measurements rather than by inaccurate size brackets.

We also plan to re-evaluate the accuracy of the proposed body size measurement algorithm on a larger data set of test persons with known body sizes. A sufficiently large data set may even make it possible to apply deep-learning training methods to this task, possibly even end-to-end learning body sizes from depth images, while a more moderately sized dataset could be used to automatically tune the parameters of the tracking algorithm.

One limitation of the present work is the rather small number of mobile phones with active depth cameras for which raw depth data is available and sufficiently accurate. We will continue to watch out for suitable mobile phones and plan to port the app on those mobile phones that seem suitable.

Another limitation is that currently two people are needed to use the Fitting app. We plan on evaluating whether leaning the mobile phone against the wall is a feasible option (similar to (Zalando Corporate, 2023)), making the app also usable for just one person.

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